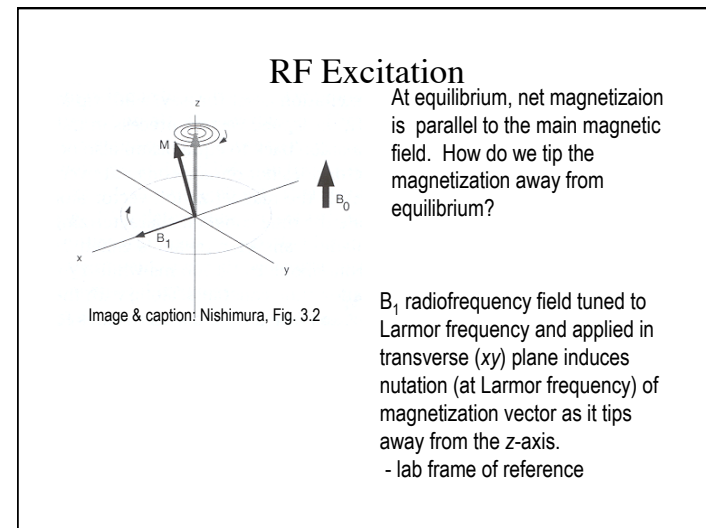
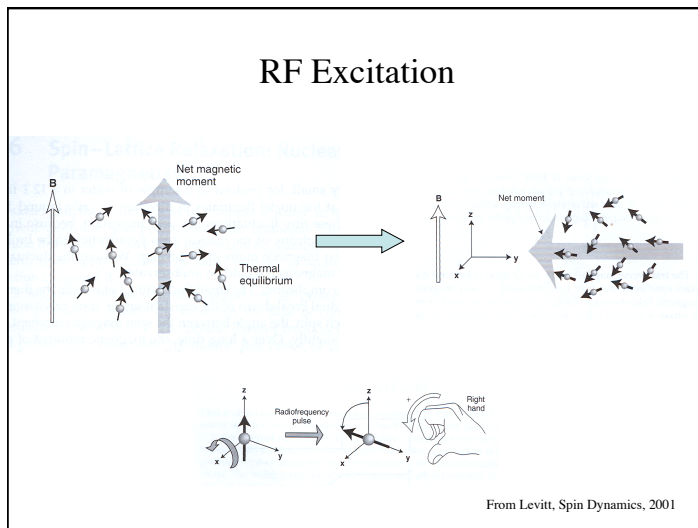
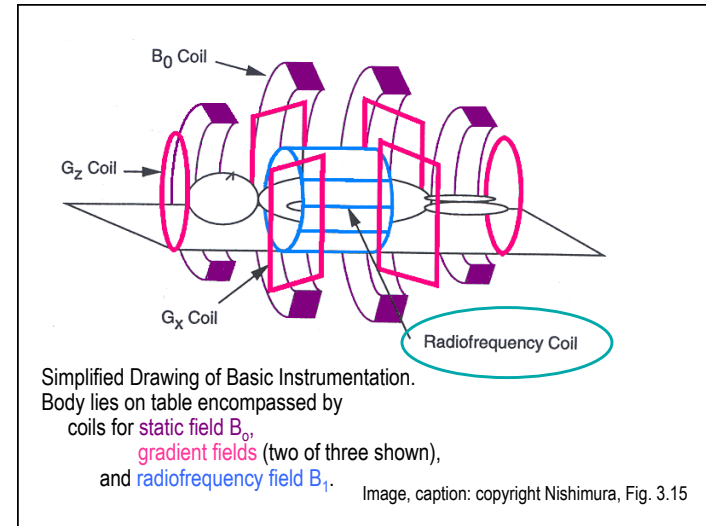
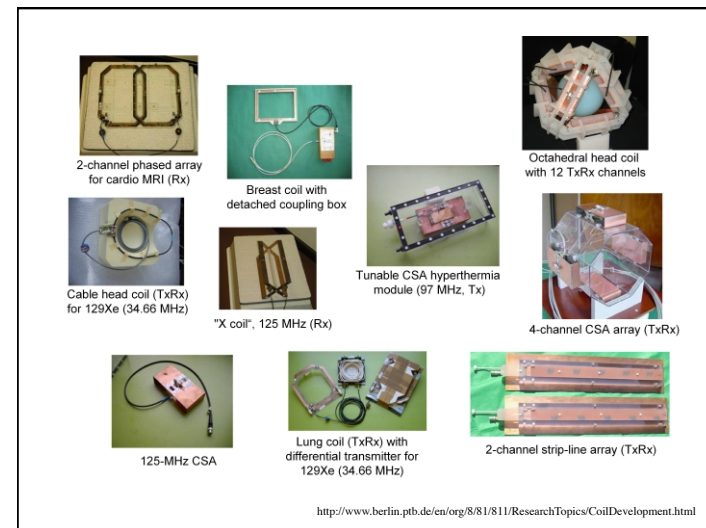
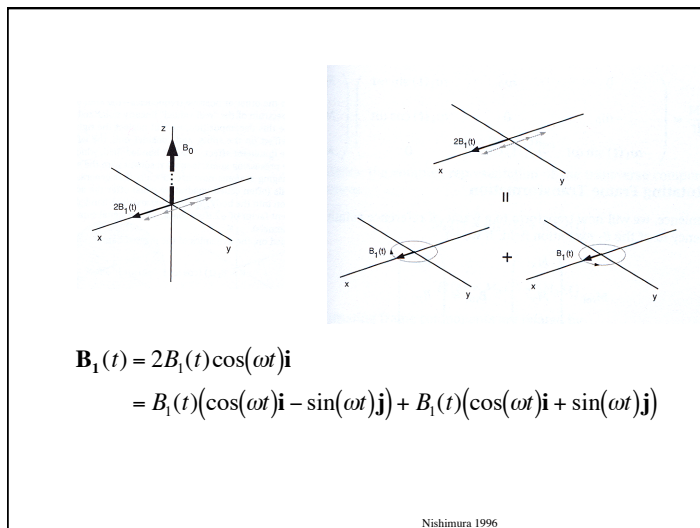
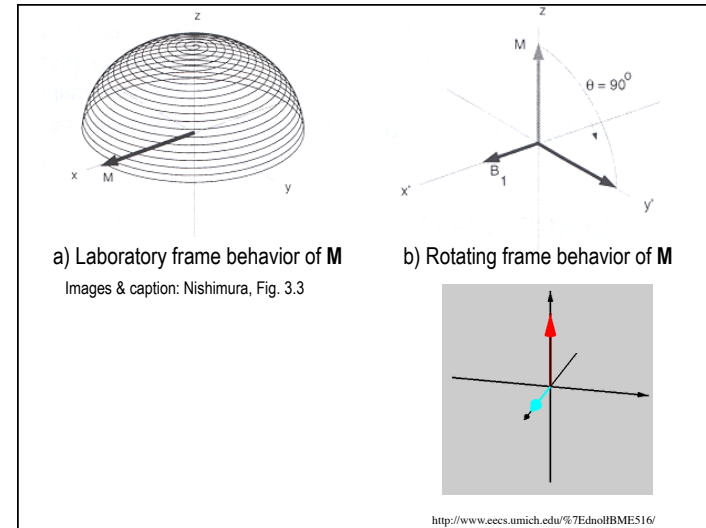
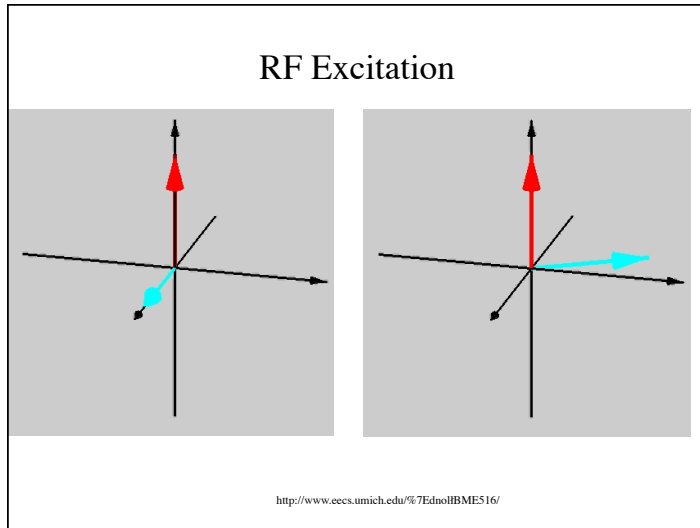


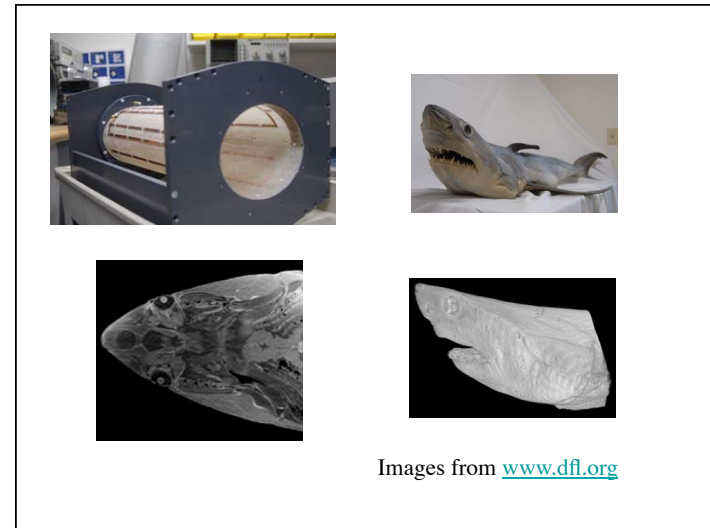
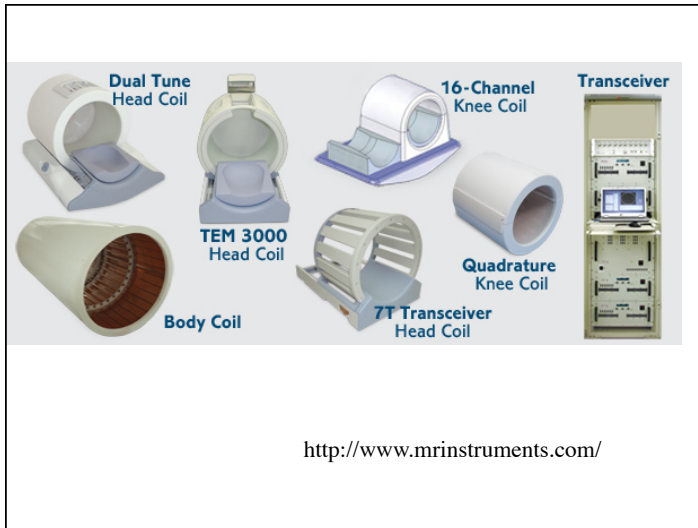
Bioengineering 280A  
Principles of Biomedical Imaging

Fall Quarter 2009  
MRI Lecture 4

Thomas Liu, BE280A, UCSD, Fall 2009







Rotating Frame Bloch Equation

$$\frac{d\mathbf{M}_{rot}}{dt} = \mathbf{M}_{rot} \times \gamma \mathbf{B}_{eff}$$

$$\mathbf{B}_{eff} = \mathbf{B}_{rot} + \frac{\omega_{rot}}{\gamma}; \quad \omega_{rot} = \begin{bmatrix} 0 \\ 0 \\ -\omega \end{bmatrix}$$

Note: we use the RF frequency to define the rotating frame. If this RF frequency is on-resonance, then the main B0 field doesn't cause any precession in the rotating frame. However, if the RF frequency is off-resonance, then there will be a net precession in the rotating frame that is give by the difference between the RF frequency and the local Larmor frequency.

Let  $\mathbf{B}_{rot} = B_1(t)\mathbf{i} + B_0\mathbf{k}$

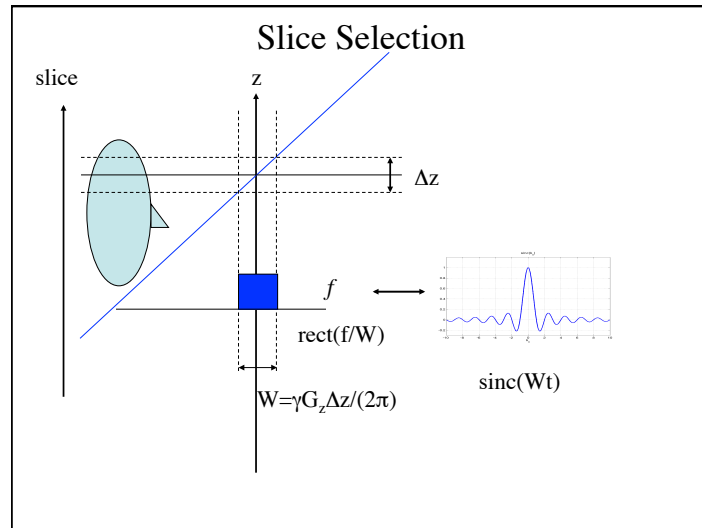
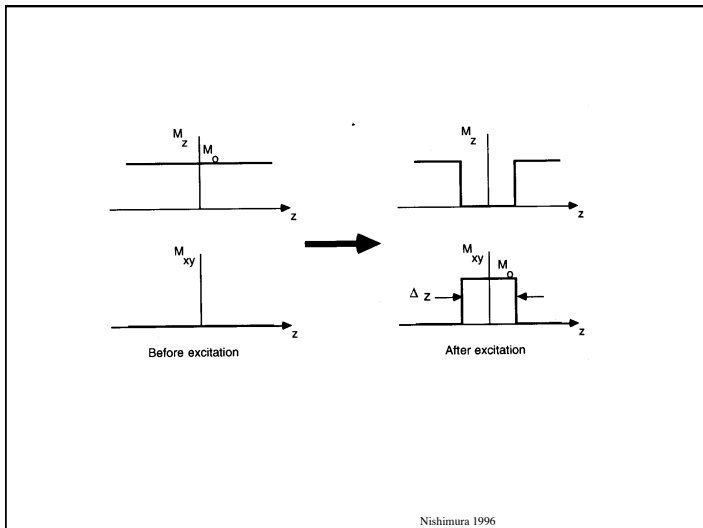
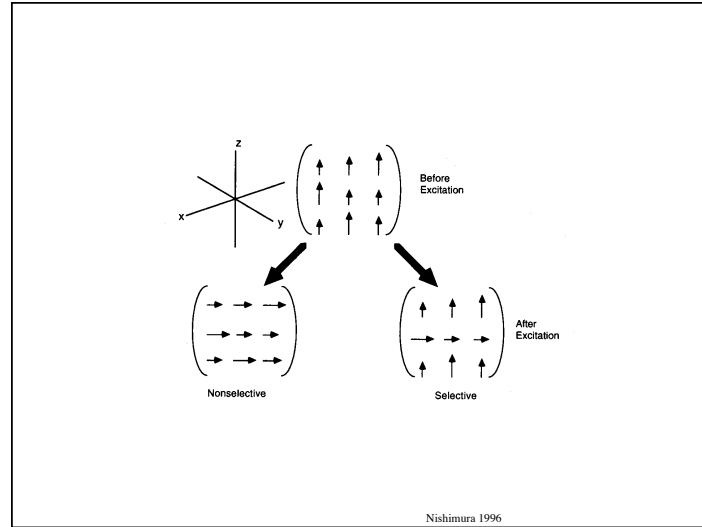
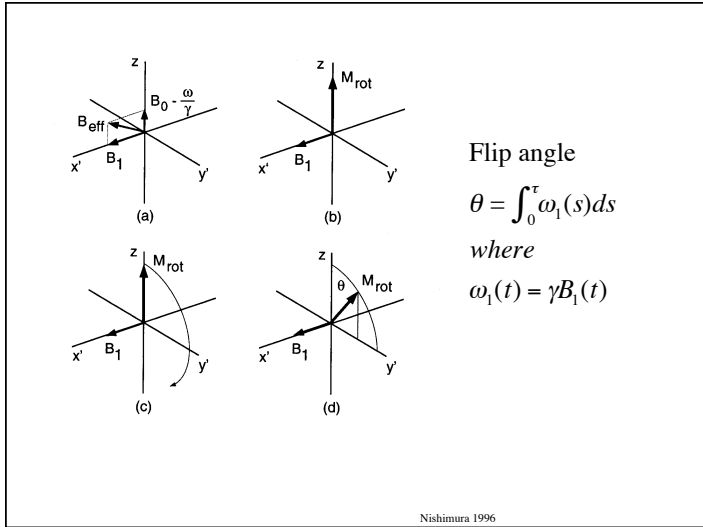
$$\mathbf{B}_{eff} = \mathbf{B}_{rot} + \frac{\omega_{rot}}{\gamma}$$

$$= B_1(t)\mathbf{i} + \left( B_0 - \frac{\omega}{\gamma} \right) \mathbf{k}$$

If  $\omega = \omega_0$

$$= \gamma B_0$$

Then  $\mathbf{B}_{eff} = B_1(t)\mathbf{i}$

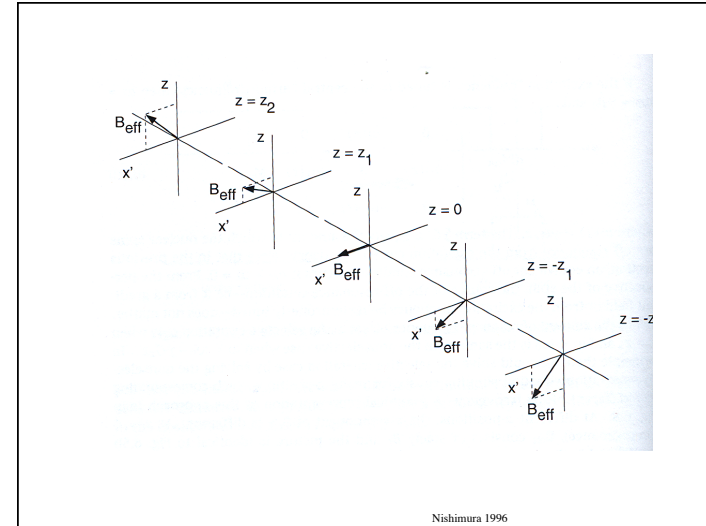


Let  $\mathbf{B}_{rot} = B_1(t)\mathbf{i} + (B_0 + \gamma G_z z)\mathbf{k}$

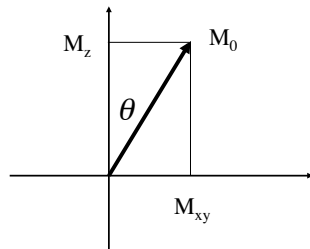
$$\begin{aligned} \mathbf{B}_{eff} &= \mathbf{B}_{rot} + \frac{\omega_{rot}}{\gamma} \\ &= B_1(t)\mathbf{i} + \left( B_0 + \gamma G_z z - \frac{\omega}{\gamma} \right) \mathbf{k} \end{aligned}$$

If  $\omega = \omega_0$

$$\mathbf{B}_{eff} = B_1(t)\mathbf{i} + (\gamma G_z z)\mathbf{k}$$



### Small Tip Angle Approximation



For small  $\theta$

$$M_z = M_0 \cos \theta \approx M_0$$

$$M_{xy} = M_0 \sin \theta \approx M_0 \theta$$

### Excitation k-space

At each time increment of width  $\Delta\tau$ , the excitation  $B_1(\tau)$  produces an increment in magnetization of the form  $\Delta M_{xy} \approx jM_0\gamma B_1(\tau)\Delta\tau$  (small tip angle approximation)

In the presence of a gradient, this will accumulate phase of the form  $\varphi = -\gamma \int_{\tau}^t z G_z(s) ds$ , such that the incremental magnetization at time  $t$  is

$$\Delta M_{xy}(t, z; \tau) = jM_0\gamma B_1(\tau) \exp\left(-j\gamma \int_{\tau}^t z G_z(s) ds\right) \Delta\tau$$

Integrating over all time increments, we obtain

$$\begin{aligned} M_{xy}(t, z) &= jM_0 \int_{-\infty}^t \gamma B_1(\tau) \exp\left(-j\gamma \int_{\tau}^t z G_z(s) ds\right) d\tau \\ &= jM_0 \int_{-\infty}^t \gamma B_1(\tau) \exp(j2\pi k(\tau, t)z) d\tau \end{aligned}$$

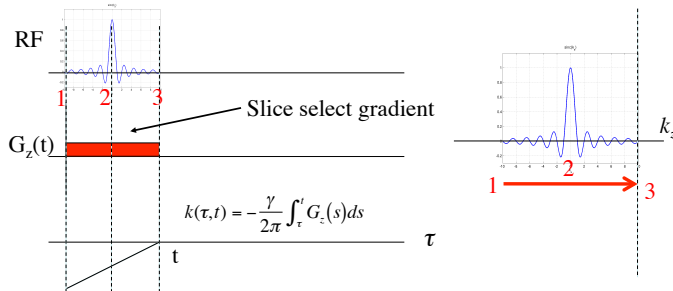
where  $k(\tau, t) = -\frac{\gamma}{2\pi} \int_{\tau}^t G_z(s) ds$

Pauly et al 1989

### Excitation k-space

$$M_{xy}(t, z) = jM_0 \int_{-\infty}^t \gamma B_1(\tau) \exp(j2\pi k(\tau, t)z) d\tau$$

This has the form of an inverse Fourier transform, where we are integrating the contributions of the field  $B_1(\tau)$  at the k-space point  $k(\tau, t)$ .



### Excitation k-space

For a constant gradient:

$$k_z(\tau, t) = \frac{\gamma}{2\pi} G_z(\tau - t) \implies \tau = \frac{2\pi}{\gamma G_z} k_z + t$$

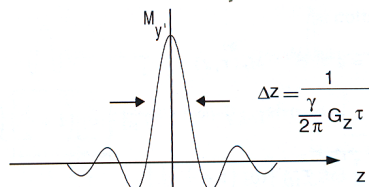
$$d\tau = \frac{2\pi}{\gamma G_z} dk_z$$

$$\begin{aligned} M_{xy}(t, z) &= jM_0 \int_{-\infty}^t \gamma B_1(\tau) \exp(j2\pi k(\tau, t)z) d\tau \\ &= jM_0 \int_{-\infty}^t \gamma B_1\left(\frac{2\pi}{\gamma G_z} k_z + t\right) \exp(j2\pi k_z z) \frac{2\pi}{\gamma G_z} dk_z \\ &= jM_0 \exp(-j\gamma G_z t z) \int_{-\infty}^t \gamma B_1(k_z) \exp\left(j2\pi k_z \left(\frac{\gamma G_z}{2\pi} z\right)\right) dk_z \\ &= jM_0 \exp(-j\omega(z)t) F^{-1}\left[\gamma B_1(k_z)\right]_{\frac{\gamma G_z}{2\pi} z} \end{aligned}$$

### Small Tip Angle Example

$$B_1(t) = B_1 \text{rect}\left(\frac{t}{\tau}\right)$$

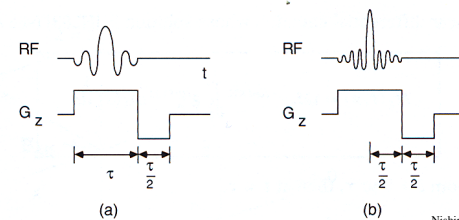
$$\begin{aligned} M_x(\tau/2, z) &= jM_0 \exp(-j\omega(z)\tau/2) F^{-1}\left[\omega_1 \text{rect}\left(\frac{k_z}{\tau}\right)\right]_{\frac{\gamma G_z}{2\pi} z} \\ &= jM_0 \exp(-j\omega(z)\tau/2) \omega_1 \tau \text{sinc}\left(\frac{\gamma G_z \tau}{2\pi} z\right) \end{aligned}$$



Nishimura 1996

### Refocusing

$$\begin{aligned} M_x(\tau, z) &= \exp(j\omega(z)\tau/2) M_x(\tau/2, z) \\ &= jM_0 \exp(j\omega(z)\tau/2) \exp(-j\omega(z)\tau/2) F^{-1}\left[\gamma B_1(k_z)\right]_{\frac{\gamma G_z}{2\pi} z} \\ &= jM_0 F^{-1}\left[\gamma B_1(k_z)\right]_{\frac{\gamma G_z}{2\pi} z} \end{aligned}$$

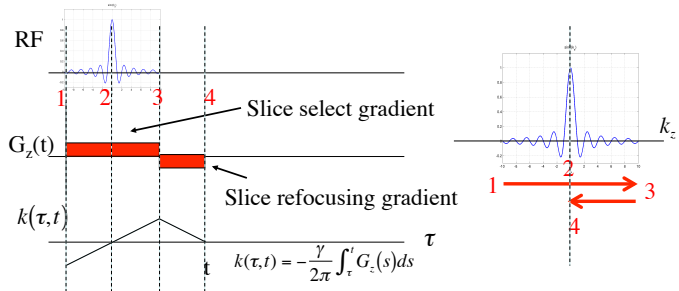


Nishimura 1996

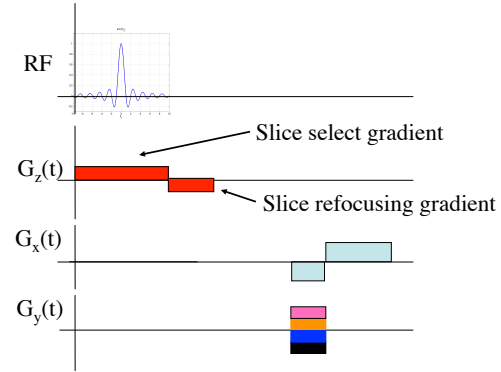
### Refocusing

$$M_{xy}(t, z) = jM_0 \int_{-\infty}^t \gamma B_1(\tau) \exp(j2\pi k(\tau, t)z) d\tau$$

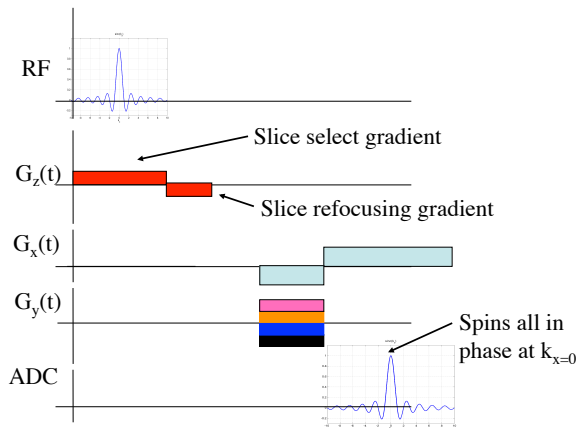
This has the form of an inverse Fourier transform, where we are integrating the contributions of the field  $B_1(\tau)$  at the  $k$ -space point  $k(\tau, t)$ .



### Slice Selection



### Gradient Echo

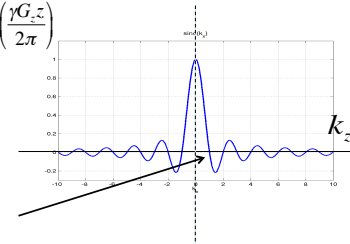


### Small Tip Angle Example

$$B_1(t) = A \operatorname{sinc}(t/\tau) \left( 0.5 + 0.46 \cos\left(\frac{2\pi t}{\tau}\right) \right)$$

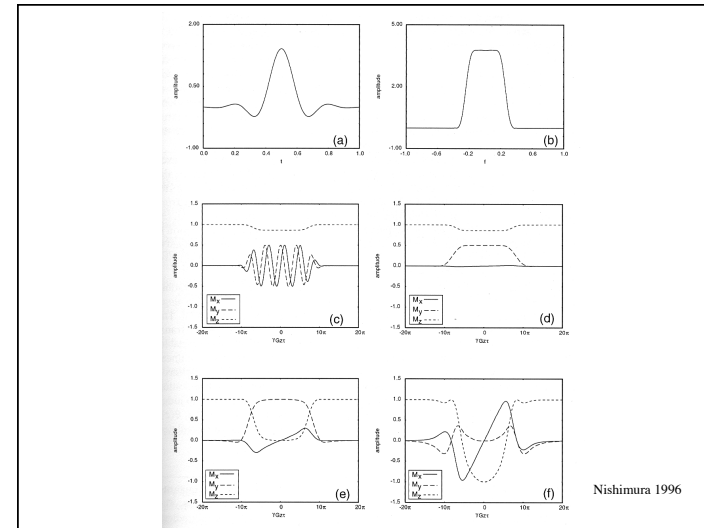
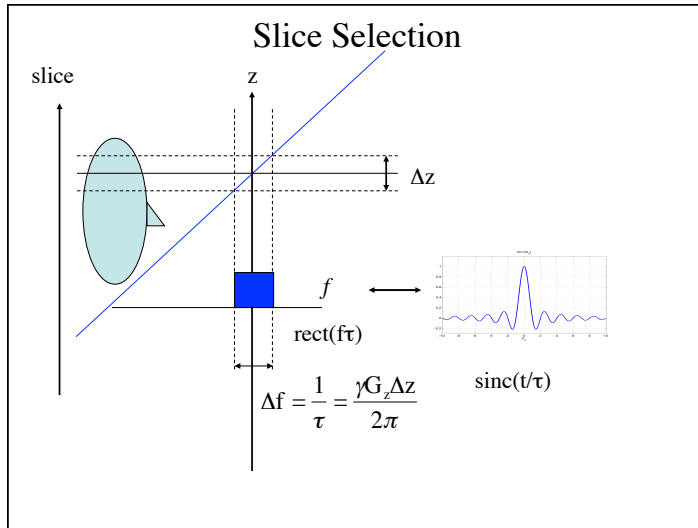
$$= A \operatorname{sinc}(t/\tau) w(t)$$

$$F^{-1}(B_1(k_z)) \Big|_{\gamma G_z z} = A\tau \operatorname{rect}\left(\frac{\gamma G_z z \tau}{2\pi}\right) * W\left(\frac{\gamma G_z z}{2\pi}\right)$$



First zero in  $k_z$  space is at  $\frac{\gamma G_z \tau}{2\pi}$ .

Therefore, width of the rect function is  $\Delta z = \frac{2\pi}{\gamma G_z \tau}$



**Example**

$\Delta z = 5 \text{ mm}; \tau = 400 \text{ } \mu\text{sec}; \theta = \pi/2$

$$G_z = \frac{2\pi}{\gamma \Delta z \tau} = \frac{1}{(4257 \text{ Hz/G})(0.5 \text{ cm})(400e-6)} = 1.175 \text{ G/cm}$$

$$\theta \approx \gamma \int_0^T B_1 \text{sinc}\left(\frac{s-T/2}{\tau}\right) ds \approx \gamma B_1 \cdot (\text{area of sinc}) = \gamma B_1 \tau$$

$$B_1 = \frac{\theta}{\gamma \tau} = \frac{\pi/2}{2\pi(4257 \text{ Hz/G})(400e-6)} = 0.1468 \text{ G}$$

### Time-Bandwidth Product (TBW)

$$\text{sinc}(t/\tau) \text{rect}\left(\frac{t}{2N\tau}\right) \Rightarrow \tau \text{rect}(t/\tau) * 2N\tau \text{sinc}(2Nt/\tau)$$

Duration =  $2N\tau$

Bandwidth =  $\frac{1}{\tau} \Rightarrow \Delta z = \frac{2\pi}{\gamma G_z \tau}$  N = number of zeros in Sinc

Transition Width =  $\frac{1}{2N\tau} \Rightarrow \Delta z' = \frac{2\pi}{\gamma G_z 2N\tau}$

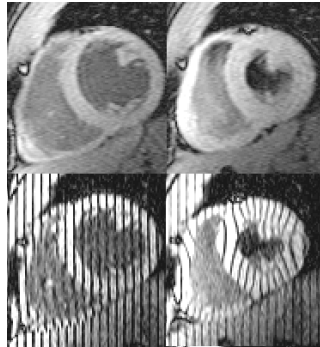
Time - Bandwidth Product (TBW) =  $2N\tau \frac{1}{\tau} = 2N$

also,  $\text{TBW} = \frac{\text{Bandwidth}}{\text{Transition Width}}$

For a fixed duration pulse, we can increase TBW by increasing the Bandwidth.  
 (Note : this will also lead to an increase in N).  
 This will require a higher B1 amplitude and a higher gradient to keep the slice width constant -- note that with higher TBW the physical transition width then decreases.



### Cardiac Tagging



### Multi-dimensional Excitation k-space

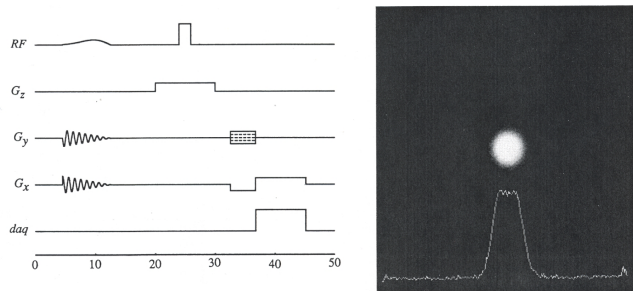
$$M_{xy}(t, \mathbf{r}) = jM_0 \int_{-\infty}^t \omega_1(\tau) \exp\left(-j\gamma \int_{\tau}^t \mathbf{G}(s) \cdot \mathbf{r} ds\right) d\tau$$

$$= jM_0 \int_{-\infty}^t \omega_1(\tau) \exp(j2\pi \mathbf{k}(\tau) \cdot \mathbf{r}) d\tau$$

where  $\mathbf{k}(\tau) = -\frac{\gamma}{2\pi} \int_{\tau}^t \mathbf{G}(t') dt'$

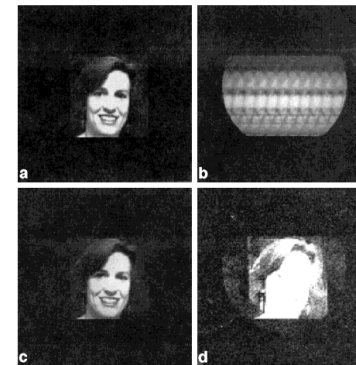
Pauly et al 1989

### Excitation k-space



Pauly et al 1989

### Excitation k-space



Panych MRM 1999